

CSCB63 – Design and Analysis of Data Structures

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¹based on notes by Anna Bretscher and Albert Lai

mergeable heaps

Recall the heap data structure:

- `insert(j , p)`: insert job j with priority p
- `max()` or `min()`: return job with max/min priority
- `extract-max()` or `extract-min()`: remove and return job with max/min priority
- `increase-priority(j , p')`: increase priority of job j to p' (optional)

mergeable heaps

Recall the heap data structure:

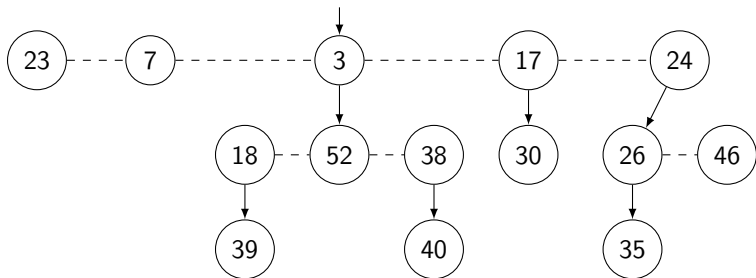
- `insert(j , p)`: insert job j with priority p
- `max()` or `min()`: return job with max/min priority
- `extract-max()` or `extract-min()`: remove and return job with max/min priority
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Does not support:

- `union(H_1 , H_2)`: merge / union two heaps H_1 and H_2

Fibonacci (min-)heap

- a forest of (min-)heaps:
 - parent priority \leq child priority
 - siblings in circular doubly-linked list; parent points to one arbitrary child
- roots in circular doubly-linked list
- pointer to minimum-priority root



binary heap vs Fibonacci heap

	binary heap worst-case	Fibonacci heap amortised
insert	$\Theta(\log n)$	$\Theta(1)$
extract-min	$\Theta(\log n)$	$O(\log n)$
decrease-priority	$\Theta(\log n)$	$\Theta(1)$
union	$\Theta(n)$	$\Theta(1)$

binary heap vs Fibonacci heap

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If Prim's algorithm uses a Fibonacci heap:

- if $n = |V|$ and $m = |E|$, then we have
- n calls of `extract-min`:
- and up to m calls of `decrease-priority`:

for a total of:

Fibonacci heap: fields

Each node has:

- *key*: priority
- *left*, *right*: for circular list of siblings
- *parent*: pointer to parent
- *child*: pointer to one child
- *degree*: number of children
- *marked*: boolean, important during decrease-priority

The heap has:

- *root_list*: a circular doubly-linked list of roots of the heaps
- *min*: pointer to root node with minimum *key*

Fibonacci heap: insert

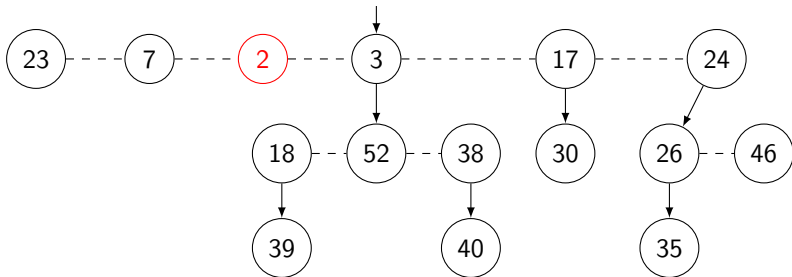
`insert(H, k):`

0. `new_root := new node(key=k, marked=false)`
1. add `new_node` to `H.root_list`
2. if `k < H.min.key`:
3. `H.min = new_root`

Fibonacci heap: insert

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Fibonacci heap: union

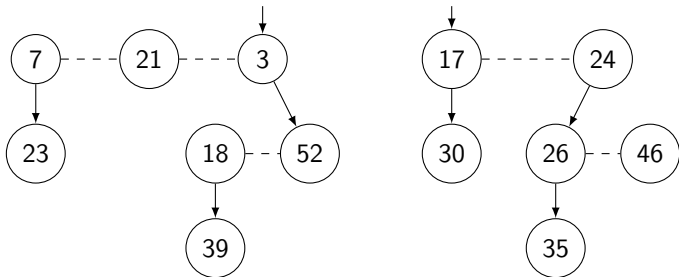
```
union(H, H_1, H_2):
```

0. `H.root_list := H_1.root_list + H_2.root_list`
1. `if H_1.min.key <= H_2.min.key:`
2. `H.min := H_1.min`
3. `else:`
4. `H.min := H_2.min`

Fibonacci heap: union

`union(H, H_1, H_2):`

0. `H.root_list := H_1.root_list + H_2.root_list`
1. `if H_1.min.key <= H_2.min.key:`
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3. `else:`
4. `H.min := H_2.min`



Fibonacci heap: insert and union

- Complexity of insert:
- Complexity of union:
- “Real work” is in extract-min and decrease-priority

Fibonacci heap: extract-min

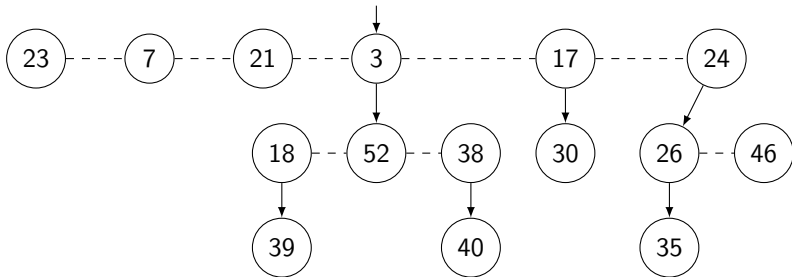
extract-min(H):

0. remove H.min from H.root_list
1. add each child of H.min to H.root_list
2. H.min := any former child of H.min // can be wrong!
3. consolidate(H) // real work here

Fibonacci heap: extract-min

extract-min(H):

0. remove H.min from H.root_list
1. add each child of H.min to H.root_list
2. H.min := any former child of H.min // can be wrong!
3. consolidate(H) // real work here



consolidate: idea

Want:

- end with root list with nodes of unique degree

Idea:

- repeat until all nodes in root list have unique degree:
 - walk through root list
 - remember degree of each node so far
 - if see a node x with degree same as that of already seen y ,
 - $u := x$ or y , whoever's key is larger
 - $v := x$ or y , whoever's key is smaller
 - add u to children of v
 - remove u from root list
- update min

How to remember degrees of nodes?

consolidate: idea

Want:

- end with root list with nodes of unique degree

Idea:

- repeat until all nodes in root list have unique degree:
 - walk through root list
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 - add u to children of v
 - remove u from root list
- update *min*

How to remember degrees of nodes?

- maintain array A of pointers
- $A[i]$ is root node with degree i

consolidate: example



consolidate: algorithm

consolidate(H):

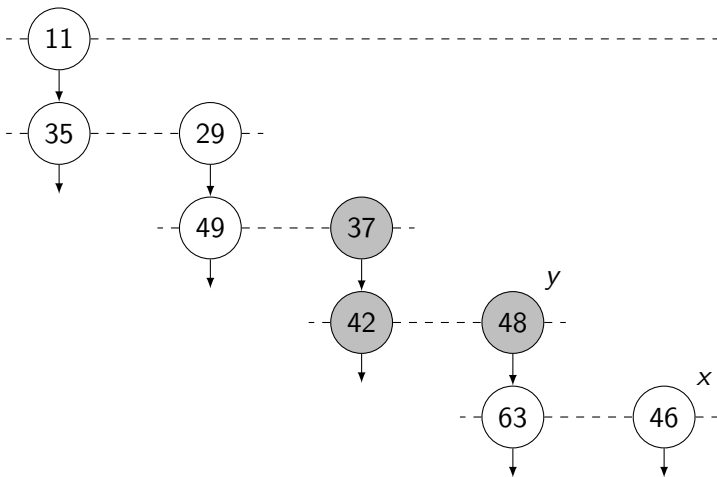
0. for each node n in H.root_list:
 1. x := n
 2. while A[x.degree] != null:
 3. y := A[x.degree]
 4. A[x.degree] := null
 5. if x.key > y.key:
 6. x, y := y, x
 7. remove y from H.root_list
 8. make y child of x // x.degree increases
 9. y.marked := false // used later
 10. A[x.degree] := x
 11. update H.min

decrease-priority: idea

- this is where we use the `marked` field
- `marked` is *true* if this node lost a child since being removed from root list
- cut child from parent: move child to root list and unmark it
- cascading cuts from some child node:
 - keep going up to root
 - if see an unmarked child, mark it and stop
 - if see a marked child, cut it and keep going

decrease-priority: example

decrease-priority($x, 46$). $y.key > x.key$, will promote x .



decrease-priority: algorithm

```
decrease-priority(H, x, k):
0. if k >= x.key: return
1. x.key := k
2. y := x.parent
3. if y != null and y.key > x.key:
4.   cut(H, x, y)
5.   while y.parent != null:
6.     if not y.marked:
7.       y.marked := true
8.       break
9.     else:
10.      cut(H, y, y.parent)
11.      y := y.parent
12. if x.key < H.min.key:
13.   H.min := x
```

decrease-priority: cut

cut(H, x, y):

0. remove x from children of y
1. add x to H.root_list
2. x.marked := false
3. if x.key < H.min.key:
4. H.min := x

complexity of Fibonacci heap operations

- Look at actual worst case time first
- Then define our potential function
- Then find amortised complexity of operations

complexity: actual costs

- define
 - $t(H)$: number of trees in heap (nodes in the root list)
 - $d(H)$: degree of node with maximum degree in heap
- $\text{insert}(j, p)$:
- $\text{min}()$:
- $\text{extract-min}()$:
 - remove node from root list:
 - insert children into root list:
 - $\text{consolidate}(H)$:
 - how many times can a root become a child of another root?
 - \therefore max number of merges:
 - find new min:
 - total:

complexity: actual costs

- define
 - $t(H)$: number of trees in heap (nodes in the root list)
 - $d(H)$: degree of node with maximum degree in heap
 - $m(H)$: number of marked nodes in heap
- decrease-priority(n , p):
 - set new priority of n :
 - if heap not ordered, cut n :
 - if cascading cuts:
 - only cut marked nodes during cascading cuts:
 - so decrease-priority is

complexity: observations

Observations AKA potential function magic:

- `extract-min` moves nodes from root list down
- `decrease-priority` cuts nodes / moves them up to root list
- `extract-min`:
- `decrease-priority`:
- define potential function:

$$\Phi(H) = t(H) + 2 * m(H)$$

- Initially:

complexity: insert

- Potential function: $\Phi(H) = t(H) + 2 * m(H)$
- How does insert change potential:

- Then amortised complexity is:

complexity: decrease-priority

- Potential function: $\Phi(H) = t(H) + 2 * m(H)$
- How does decrease-priority change potential?
- if we make x cuts
- for each cut, a node added to root list:
 - every cut unmarks a marked node
 - $x - 1$ or x nodes become unmarked
 - at most 1 node becomes marked
 - then:

complexity: decrease-priority

Have:

- $\Phi(H) = t(H) + 2 * m(H)$
- $t(H_i) = t(H_{i-1}) + x$
- $m(H_i) \leq m(H_{i-1}) - x + 2$

Then:

Amortised cost:

complexity: extract-min

- Potential function: $\Phi(H) = t(H) + 2 * m(H)$
- How does extract-min change potential?
- no nodes become marked, some may become unmarked
 - $m(H_i) \leq m(H_{i-1})$
- after extract-min (after consolidate), all nodes in root list have different degree
- then:

Then

complexity: extract-min

- recall actual time: $t(H_{i-1}) + d(H_i)$
- change in $\Delta(\Phi) \leq d(H_i) + 1 - t(H_{i-1})$
- Then

complexity: extract-min

- $a_i \in \mathcal{O}(d(H_i))$
- Last piece of the puzzle: a bound on $d(H)$
- What is the maximum degree of a root node in a heap of size n ?
- What is the minimum number of nodes $N(d)$ in a heap with root nodes of degree d ?
- ...
- In tutorial show $N(d) = \text{fib}(d + 2)$ — hence the name “Fibonacci heap”!
• $\therefore n \geq \phi^d$
• $\therefore d \leq \log_{\phi} n$

Fibonacci heap: complexity

- insert: amortised $\mathcal{O}(1)$
- extract-min: amortised $\mathcal{O}(\log n)$
- decrease-priority: amortised cost $\mathcal{O}(1)$